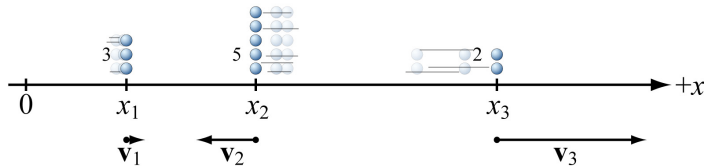


# Center of mass

## Mass-averaged position



$$x_{\text{C.O.M.}} = \frac{\overbrace{x_1 + x_1 + x_1}^{3 \text{ copies}} + \overbrace{x_2 + \dots + x_2}^{5 \text{ copies}} + \overbrace{x_3 + x_3}^{2 \text{ copies}}}{10}$$

$$x_{\text{C.O.M.}} = \frac{3}{10}x_1 + \frac{5}{10}x_2 + \frac{2}{10}x_3$$

$$x_{\text{C.O.M.}} := \frac{m_1}{M}x_1 + \frac{m_2}{M}x_2 + \dots + \frac{m_N}{M}x_N$$

## Mass-averaged velocity

$$v_{x,\text{C.O.M.}} = \frac{\Delta x_{\text{C.O.M.}}}{\Delta t} = \frac{x_{\text{C.O.M.},f} - x_{\text{C.O.M.},i}}{\Delta t}$$

$$v_{x,\text{C.O.M.}} = \frac{\left(\frac{m_1}{M}x_{1,f} + \dots + \frac{m_N}{M}x_{N,f}\right) - \left(\frac{m_1}{M}x_{1,i} + \dots + \frac{m_N}{M}x_{N,i}\right)}{\Delta t}$$

$$v_{x,\text{C.O.M.}} = \frac{m_1}{M} \frac{\Delta x_1}{\Delta t} + \frac{m_2}{M} \frac{\Delta x_2}{\Delta t} + \dots + \frac{m_N}{M} \frac{\Delta x_N}{\Delta t}$$

$$v_{x,\text{C.O.M.}} = \frac{m_1}{M}v_{x,1} + \frac{m_2}{M}v_{x,2} + \dots + \frac{m_N}{M}v_{x,N}$$

## Mass-averaged acceleration

$$a_{x,\text{C.O.M.}} = \frac{m_1}{M}a_{x,1} + \frac{m_2}{M}a_{x,2} + \dots + \frac{m_N}{M}a_{x,N}$$

If  $\sum_{\text{EXT ON SYS}} F_x = 0$  and  $v_{x,\text{C.O.M.},i} = 0$ ,

$$x_{\text{C.O.M.},i} = x_{\text{C.O.M.},f}$$

### Neatly and graphically represent situation(s)

- Draw before and after situations
- Choose reference position and positive direction

### Graphically represent quantities and their relationships

- Specify a marked position on each object (if possible, choose markers that are initially at the same position)

### Identify relevant allowed starting point (in)equation(s)

- Relative displacement formula:  $x_{A,C} = x_{A,B} + x_{B,C}$
- Constancy of center of mass:  $x_{\text{C.O.M.},i} = x_{\text{C.O.M.},f}$

### Analyze

### Communicate

Problem type: Person walks on boat, causing it to slide across water

is the velocity of a particle with mass and momentum equal to the total mass and total momentum, respectively, of the system

$$v_{x,\text{C.O.M.}} = \frac{m_1v_{x,1} + m_2v_{x,2} + \dots + m_Nv_{x,N}}{M}$$

$$v_{x,\text{C.O.M.}} = \frac{p_{x,1} + p_{x,2} + \dots + p_{x,N}}{M}$$

$$v_{x,\text{C.O.M.}} = \frac{\sum p_x}{M}$$

$$Mv_{x,\text{C.O.M.}} = \sum p_x$$

In the C.O.M. frame,  $v_{x,\text{C.O.M.}} = 0$  and  $\sum p_x = 0$ .

Problem type: Going into C.O.M. frame to solve elastic collisions

is proportional to net force on system from external sources

$$a_{x,\text{C.O.M.}} = \frac{m_1a_{x,1} + m_2a_{x,2} + \dots + m_Na_{x,N}}{M}$$

$$a_{x,\text{C.O.M.}} = \frac{\sum_{1,\text{EXT}} F_x + \sum_{1,\text{INT}} F_x + \dots + \sum_{N,\text{EXT}} F_x + \sum_{N,\text{INT}} F_x}{M}$$

$$a_{x,\text{C.O.M.}} = \frac{\sum_{\text{EXT ON SYS}} F_x}{M}$$

Problem type: Locating fragments of projectile that explodes