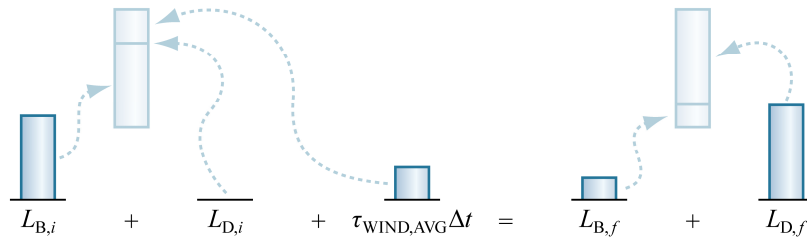
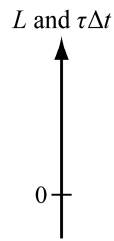
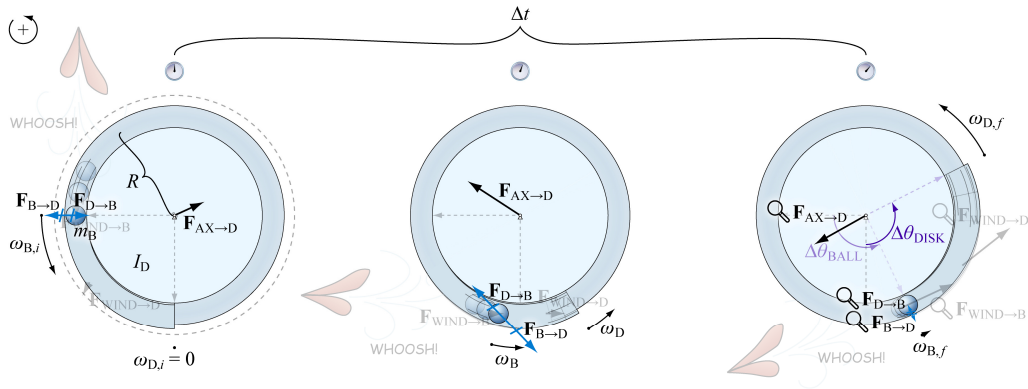
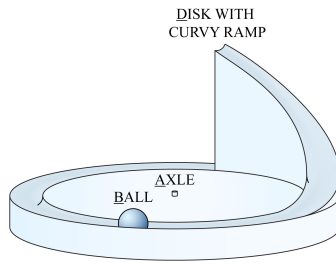
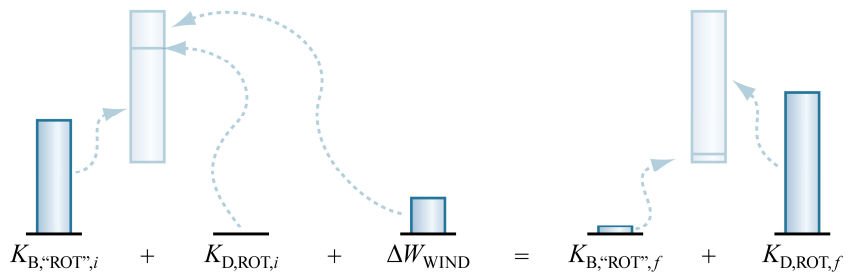
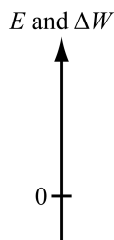


Sums of rotational quantities can be changed by input



$$\Sigma L_i + \left(\sum_{\text{EXT ON SYS}} \tau_{AVG} \right) \Delta t = \Sigma L_f$$



$$\underbrace{\Sigma K_i + \Sigma U_{G,i} + \Sigma U_{S,i}}_{\Sigma E_{SYS,i}} + \Sigma \Delta W_{OUF} = \underbrace{\Sigma K_f + \Sigma U_{G,f} + \Sigma U_{S,f}}_{\Sigma E_{SYS,f}} + \Sigma \Delta U_{INT}$$