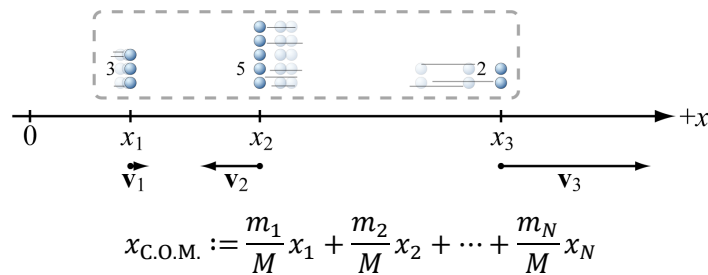


Mass-averaging by summing over point masses generalizes to integrals

For a **discrete set of masses**, each with known c.o.m.,



Neatly and graphically represent situation(s)

Graphically represent quantities and their relationships

1. Draw **diagram** of the objects, labeling each object's mass and the position of each object's c.o.m.

Identify relevant allowed starting point (in)equation(s)

2. **Substitute** into

$$x_{\text{C.O.M.}} := \frac{m_1 x_1 + m_2 x_2 + \dots + m_3 x_3}{M}$$

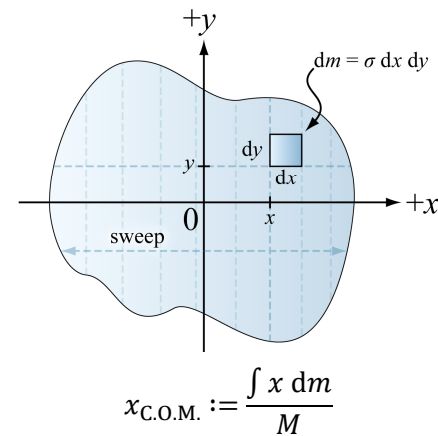
$$y_{\text{C.O.M.}} := \frac{m_1 y_1 + m_2 y_2 + \dots + m_3 y_3}{M}$$

$$z_{\text{C.O.M.}} := \frac{m_1 z_1 + m_2 z_2 + \dots + m_3 z_3}{M}$$

Analyze

Communicate

For a **continuous mass distribution**,



Neatly and graphically represent situation(s)

1. Draw large **diagram** of object.
2. Label the **boundary functions**.
3. Label the points of **intersection**.

Graphically represent quantities and their relationships

4. Draw a small 1-dimensional **differential length element** $d\ell$, a small 2-dimensional **differential area element** dA or a small 3-dimensional **differential volume element** dV in the interior/bulk of the object.

Identify relevant allowed starting point (in)equation(s)

5. Draw an arrow pointing to that differential portion of the object, labeling it with its **differential mass**, $dm = \lambda \, d\ell$, $dm = \sigma \, dA$, or $dm = \rho \, dV$.
6. **Write** relevant integral expression(s).

$$x_{\text{C.O.M.}} := \frac{\int_{\text{FORM}} x \, dm}{M} \quad y_{\text{C.O.M.}} := \frac{\int_{\text{FORM}} y \, dm}{M} \quad z_{\text{C.O.M.}} := \frac{\int_{\text{FORM}} z \, dm}{M}$$

Analyze

7. **Substitute** differential mass element into integral expression(s) and **integrate**.

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